

# remote-controlled racing car

Scan the code to watch the installation video tutorial





Remote control racing is mainly realized using the principle of wireless remote control. The remote control converts control instructions (forward, turn, etc.) into low-frequency coded signals through an encoding circuit, which are modulated and transmitted by the antenna. After the antenna at the trolley end receives the signal, the encoded signal is demodulated by the super regenerative circuit, and then the command is recognized by the decoding chip, and the motor is driven to perform corresponding actions. Without any obstruction or interference, the remote control distance is 5 to 7 meters.

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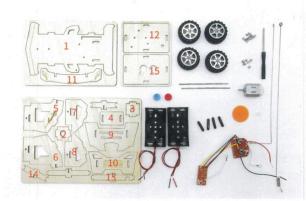
Children all have 100,000 whys, bring H/S here to find answers!

# bill of materials

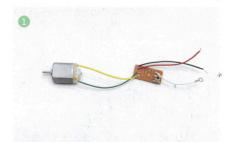
- ①Four 35 wheels
- 275mm iron shafts, 2

operation steps

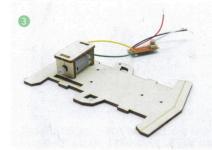
- 36mm screws, 8
- 44mm cap screws, 6
- ⑤ screwdriver, 1
- 6130 motor, 1
- 71 red button
- ®1 blue button
- 9battery boxes, 2
- 10 Insulating caps, 4
- 1050 orange gear, 1
- 1210 white gear, 1
- 13transmitting board, 1
- <sup>(4)</sup>receiving antenna each



Warm reminder: Children should pay attention to safety during the production process. All parts cannot be imported. Children should operate under the guidance of parents or teachers. If you want to complete the experiment easily, please read the instructions carefully. If you don't understand, you can watch the video or seek help from others!



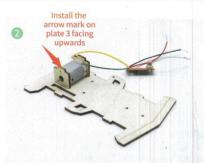
Connect the green and yellow wires of the receiving board to the positive and negative poles of the motor



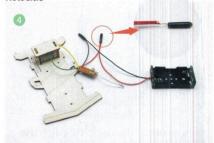
Install plate No. 4 on top of plates 2 and 3 and insert the white pinion on the motor iron shaft



As shown in the figure, use two long screws to fix the receiving plate on the No. 1 board, and use two short screws to fix the battery box on the No. 1 board



Clamp the front and rear ends of the motor with No. 2 and No. 3 plates and install them together on the No. 1 base plate, with the motor shaft facing the long hole side



Connect the remaining red and black wires on the receiving board with the red and black wires on the battery box correspondingly, and cover the connecting wires with the insulating cap



Use a short screw to pass through the white wire metal hole on the receiving plate, then pass through the round hole of the right-angle antenna, and then fix it on the No. 1 plate as shown in the figure.



















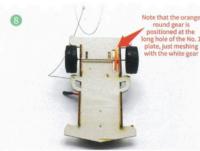
As shown in the figure, install four wooden boards No. 5, 6, 7 and 8 on both sides of No. 1 board respectively



Pass another iron axle through the round holes of No. 7 and No. 8 plates, and install the wheels on both sides of the iron axle



As shown in the figure, use two long screws to fix the launch plate to the middle position of the No. 12 plate



Turn over the No. 1 plate, pass the iron shaft through the No. 5 plate, the orange round gear and the No. 6 plate in turn, and install the wheels on both sides of the iron shaft



Turn the car body over again, install the No. 9, 10, and 11 plates from front to back on the top and rear sides, and partially install the trolley



Pass the red black line of the battery box through the round hole on the back of the No. 12 board, and then connect it to the red and black lines of the launch board correspondingly. Cover the connection position with an insulating cap



Use a short screw to pass through the metal ring on the white line of the transmitter board and the metal round hole on the long straight antenna in turn and fix it at the position shown on the No. 12 board.



Install the No. 15 plate above as shown



Press the red and blue buttons firmly on the remote control button on the launch pad



Assemble the No. 13 plate and No. 14 plate with a tick shape and install them on the No. 12 bottom plate, with two screw holes facing downward and the other two facing upward



Use 4 long screws to fix them on the upper and lower sides respectively



The remote control racing car is installed!

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